

# University of Malta

# Junior College



End of Year Test

Worked Solutions

(i)  $\mathbf{F} = \sum \mathbf{F}_i = (8 + 6 - 2)\mathbf{i} + (4 + 5 - 2 - 2)\mathbf{j} = (12\mathbf{i} + 5\mathbf{j}) \text{ N}$  $\Rightarrow$  magnitude of  $\mathbf{F} = |\mathbf{F}| = \sqrt{12^2 + 5^2} = 13 \text{ N}$ 

Let  $\theta$  be the angle that **F** makes with the horizontal, then

$$
\tan \theta = \frac{5}{12} \implies \theta = \tan^{-1} \left( \frac{5}{12} \right) = \frac{22.6^{\circ}}{22.5^{\circ}}
$$



(ii) Clockwise moment about *O*:  $6(3) + 2(4) + 2(3) - 2(4) = 12c$  $\Rightarrow$  24=12*c* i.e.  $c = 2$  m Hence the line of action of  $\bf{F}$  passes through the point  $(0, 2)$ .

The equation of the line is  $y = \frac{5}{12}x + 2$  or  $12y = 5x + 24$ 12  $y = \frac{5}{12}x + 2$  or  $12y = 5x +$ 

(iii) From part (ii), the clockwise moment about *O* is  $12(2) = 24$  Nm Hence the magnitude of  $C = |C| = 24$  Nm



 Since the lines of action of the weight and the friction are fixed, then using the 3 – force result, the line of action of the reaction passes through the intersection of the other two.

 (ii) From symmetry, the centre of mass of a cylinder lies on the axis of the cylinder at a distance of half the vertical height i.e. a distance of 2  $\frac{3d}{2}$  from its base.

> For limiting equilibrium, the centre of mass must lie exactly vertically above the lowest point of contact.



By referring to the diagram, the maximum angle occurs when

$$
\tan \alpha = \frac{\frac{d}{2}}{\frac{3d}{2}} = \frac{1}{3} \qquad \Rightarrow \quad \alpha = \tan^{-1} \left( \frac{1}{3} \right) = \frac{18.4^{\circ}}{\frac{3}{2}} = \frac{18.4^{\circ}}{\frac{3}{2}} = 12.3^{\circ}
$$

(iii)



Resolving vertically:  $R = W \cos \alpha_s$  ...(a) Resolving horizontally:  $\mu R = W \sin \alpha_s$  ...(b)

 $\frac{\mu}{\mu} = \frac{m \sin \alpha_s}{W \cos \alpha_s}$   $\Rightarrow \mu = \tan \alpha_s$ *s s W W R*  $\frac{R}{R} = \frac{W \sin \alpha_s}{W \cos \alpha} \Rightarrow \mu = \tan \alpha_s$ *a b*  $\frac{\mu R}{R} = \frac{W \sin \alpha_s}{W} \Rightarrow \mu = \tan \alpha$ cos  $=\frac{W\sin\alpha_s}{W} \Rightarrow \mu =$  $\left( a\right)$  $(b)$ 

 $\therefore$  tan  $\alpha_s = \frac{2}{5}$  for sliding 9  $\therefore$  tan  $\alpha_s = \frac{2}{\Omega}$ 





(i) From the graph  $XA = 4$  m

 $\Rightarrow$  area of triangle = 4m

Since the base of the triangle  $= 2.5$  (time),

Then  $4 = \frac{1}{2} (2.5) (V_{\text{max}})$  $4 = \frac{1}{2} (2.5) (V_{\text{max}})$ , where  $V_{\text{max}}$  is the maximum speed for this section  $\mathbf{Q}$ 

$$
\Rightarrow 8 = 2.5 V_{\text{max}} \qquad \text{i.e.} \quad V_{\text{max}} = \frac{8}{2.5} = \frac{3.2 \text{ m/s}}{}
$$

(ii) The gradient of a velocity – time graph is the acceleration

Thus Acceleration =  $3m/s^2$  = time 2  $\frac{V}{I} = \frac{V}{2}$ 

$$
\implies V = 3 * 2 = \underline{6m/s}
$$

- (iii) Area of trapezium  $=\frac{1}{2}$ (sum of parallel sides)(perpendicular height) 2 1
- $\therefore$  48 =  $\frac{1}{2}(t_c+12)^*$ 6 2  $\therefore$  48 =  $\frac{1}{2}(t_c + 12)^*$  6, by referring to the diagram below



$$
\Rightarrow 48 * 2 = (t_c + 12) * 6
$$

$$
\frac{48 * 2}{6} = t_c + 12 \Rightarrow 16 = t_c + 12
$$

i.e.  $t_c = 4$  s

Thus *P* starts its deceleration at  $t = 4.5 + 4 = 8.5$  s

(iv) The deceleration is found by finding the gradient of the last part

Deceleration = 
$$
\frac{0-6}{14.5-8.5} = \frac{-6}{6} = -1 \text{ m/s}^2
$$

∴ deceleration of  $1 \text{ m/s}^2$ 



 Given 24  $\tan \theta = \frac{7}{2}$ 

At equilibrium,

Resolving forces vertically:  $R\cos\theta - \mu R\sin\theta = mg$ 

$$
R(\cos\theta - \mu\sin\theta) = mg \dots (a)
$$

Resolving forces horizontally:

Resolving forces horizontally: 
$$
F = ma = \frac{mv^2}{r}
$$

$$
R \sin \theta + \mu R \cos \theta = \frac{mv^2}{r}
$$

$$
R(\sin \theta + \mu \cos \theta) = \frac{mv^2}{r} \dots (b)
$$
  
(b)  

$$
\frac{(b)}{(a)}
$$

$$
\frac{R(\sin \theta + \mu \cos \theta)}{R(\cos \theta - \mu \sin \theta)} = \frac{\frac{mv^2}{r}}{mg}
$$

$$
\frac{(\sin \theta + \mu \cos \theta)}{(\cos \theta - \mu \sin \theta)} = \frac{v^2}{gr}
$$
  
Dividing by  $\cos \theta$ :
$$
\frac{(\tan \theta + \mu)}{(1 - \mu \tan \theta)} = \frac{v^2}{gr}
$$

$$
\Rightarrow \qquad v^2 = \frac{rg(\tan \theta + \mu)}{(1 - \mu \tan \theta)}
$$
  
Substituting the given values 
$$
v^2 = \frac{60(10)(\frac{7}{24} + \frac{3}{7})}{(1 - (\frac{3}{2})(\frac{7}{24}))} = \frac{600(\frac{121}{168})}{\frac{147}{168}} = 493.877
$$

$$
(1 - (\frac{3}{7})(\frac{7}{24})) = \frac{147}{168}
$$
  
\n
$$
v = \sqrt{493.877} = \frac{22.22 \text{ m/s}}{}
$$



 (i) Resolving horizontally: 2  $R_c = R_c \cos 45^\circ = \frac{R_c}{\sqrt{c}}$  $\mu R_a = R_c \cos 45^\circ = \frac{R_c}{\sqrt{2}}$  ...(a)

 Resolving vertically: 2  $W = R_a + R_c \sin 45^\circ = R_a + \frac{R_c}{\sqrt{2}}$  ...(b)

Taking clockwise moments about *A*:  $W \cos 45^\circ(2a) = R_c(3a)$ 

$$
\frac{W(2a)}{\sqrt{2}} = R_c(3a) \implies R_c = \frac{W(2a)}{3a\sqrt{2}} = \frac{W\sqrt{2}}{3}...(c)
$$

 From (a)  $\mu\sqrt{2}$   $\mu\sqrt{2}$  3 3 $\mu$ 2 2 1 2  $R_a = \frac{R_c}{\sqrt{2}} = \frac{1}{\sqrt{2}} \frac{W\sqrt{2}}{r^2} = \frac{W}{2r}$ , by using the result of (c)

Substituting this result and that of (c) in (b), we get:

$$
W = \frac{W}{3\mu} + \frac{1}{\sqrt{2}} \frac{W\sqrt{2}}{3} = \frac{W}{3\mu} + \frac{W}{3}
$$

 Dividing by *W*:  $\mu$  3 3  $\mu$ 1 3  $\Rightarrow \frac{2}{3}$ 3 1 3  $1 = \frac{1}{2} + \frac{1}{2} \implies \frac{2}{3} = \frac{1}{3}$  i.e. 2  $\mu = \frac{1}{2}$ 

#### (ii) Referring to the diagram below:

 The two weights at *B* and *D* are parallel and are equidistant from the peg *C*. Thus by symmetry their resultant is 2*W* (vertically downwards) and passes through *C.*

 Thus if we consider their resultant instead of the 2 weights, we have 2 out of 3 forces in equilibrium whose line of action passes through *C.* 



 Using the 3 – force result, the total reaction *S* must pass through *C* as well.

∴ if  $\lambda$  is the angle of friction, then  $\lambda = 45^\circ$ 

$$
\implies
$$
  $\mu = \tan \lambda = \tan 45^{\circ} = 1$ 

Question 6

(a) The pendulum beats every 2 s  $\Rightarrow$  period  $T = 4$  s The frequency  $f = \frac{1}{\pi} = \frac{1}{2} = \frac{0.25 \text{ Hz}}{0.25 \text{ Hz}}$ 4  $\frac{1}{\pi} = \frac{1}{\pi} =$ *T* Using  $T = 2\pi \sqrt{2}$ *g*  $T = 2\pi \sqrt{\frac{l}{\tau}}$ 

Bringing *l* subject of the equation :  $l = \frac{gT}{4\pi^2} = \frac{g(T)}{4\pi^2} = \frac{7g}{\pi^2}$ 2 2 <sup>2</sup>  $g(4)^2$  4 4  $(4)$  $4\pi^2$   $4\pi^2$   $\pi$  $l = \frac{gT^2}{l^2} = \frac{g(4)^2}{l^2} = \frac{4g}{r^2}$ 

> (b) (i) When the particle is  $0.06$  m away from *P*, i.e.  $0.3 - 0.06 = 0.24$  m from the centre of motion, its speed is 0.9 m/s.

Using the formula:  $v^2 = \omega^2 (a^2 - x^2)$ 

Substituting  $0.9^2 = \omega^2 (0.3^2 - 0.24^2)$ 

$$
\Rightarrow 0.9^2 = \omega^2 (0.0324) \quad \text{i.e.} \quad \omega^2 = \frac{0.9^2}{0.0324} = 25
$$

 $\therefore \omega = 5 \text{ rad/s}$ 

The basic equation of S.H.M. is  $\ddot{x} = -\omega^2 x$ . Substituting  $\ddot{x} = -25x$ 

(ii) the Period 
$$
T = \frac{2\pi}{\omega} = \frac{2\pi}{5}
$$
 s

(iii) Maximum velocity occurs when  $x = 0$  (centre of motion)  $∴ v^2 = \omega^2 a^2 \implies v = \omega a = 5(0.3) = 1.5$  m/s

Maximum acceleration occurs when  $x = a$  (extremes)

$$
\therefore
$$
  $\ddot{x} = -\omega^2 x = -25(0.3) = -7.5 \text{ m/s}^2$ 

Hence magnitude of acceleration =  $7.5 \text{ m/s}^2$ 

## Question 7



10,000 N

(i) Resolving vertically the whole system:  $Y = 10,000$  N Taking anticlockwise moments at *A*: **P***l* = 10,000(2*l*).

 $\Rightarrow$  **P** = 20,000 N

(ii) Resolving horizontally the whole system:  $X = P = 20,000 N$ Let **R** be the reaction force on the framework at *A*.

$$
\mathbf{R} = \sqrt{\mathbf{X}^2 + \mathbf{Y}^2} = \sqrt{(20,000)^2 + (10,000)^2} = 22,360.7 \text{ N}
$$

Let  $\theta$  be the angle it makes with the horizontal,

 Then 2 1 20,000  $\tan \theta = \frac{10,000}{20,000} = \frac{1}{2}$   $\Rightarrow \theta = 26.57^{\circ}$ 

 (iii) From the diagram, it is clear that *BD* is neutral i.e. there is no force in *BD*  This can be easily verified because if we Resolve vertically at  $D: T_{BD} = 0$ Resolving horizontally at *A*:  $\mathbf{X} = T_{AB}$   $\Rightarrow$   $T_{AB} = 20,000 \text{ N}$ Resolving vertically at *A*:  $\mathbf{Y} = \mathbf{T}_{AE} \Rightarrow \mathbf{T}_{AE} = \frac{10,000 \text{ N}}{2}$ Resolving vertically at *C*:  $10,000 = T_{BC} \cos 45^\circ \Rightarrow T_{BC} = \frac{14142.1 \text{ N}}{250.0 \text{ N}}$ Resolving horizontally at *C*:  $T_{BC} \sin 45^\circ = C_{DC}$  $\Rightarrow$  C<sub>DC</sub> = 14142.1 sin 45<sup>0</sup> = <u>10,000 N</u> Resolving horizontally at *D*:  $C_{ED} = C_{DC} \implies C_{ED} = \frac{10,000 \text{ N}}{2}$ Resolving vertically at  $E: T_{AE} = C_{EB} \sin 45^\circ$ 

$$
\Rightarrow C_{EB} = \frac{T_{AE}}{\sin 45^\circ} = \frac{10,000}{\sin 45^\circ} = \frac{14,142.1 \text{ N}}{}
$$

 In rods *AB*, *BC* and *EA*, there is tension, while in the rods *CD*, *DE* and *BE*, there is compression. There is no force in rod *BD*.

Question 8



(i) 
$$
\mathbf{T} = \frac{\lambda x}{a}
$$

At equilibrium, resolving vertically:  $T = mg$ 

Given  $a = 0.3$  m and  $x = 0.1$  m

Substituting: 
$$
mg = \frac{\lambda(0.1)}{0.3}
$$
  $\Rightarrow \lambda = \frac{0.3(mg)}{0.1} = \frac{3mg}{}$ 

(ii)



Using 
$$
\mathbf{T} = \frac{\lambda x}{a}
$$
, we get  $\mathbf{T} = \frac{3mg(0.45 - 0.3)}{0.3} = \frac{3mg}{2}$   
At equilibrium, resolving vertically  $\mathbf{T}\cos\alpha = mg$   
Substituting  $\frac{3mg}{2}\cos\alpha = mg \implies \cos\alpha = \frac{2}{3} \implies \alpha = \frac{48.2^{\circ}}{2}$   
(iii) At equilibrium resolving horizontally  $\mathbf{P} = \mathbf{T}\sin\alpha$ 

(iii) At equilibrium, resolving horizontally  $P = T \sin \alpha$ 

$$
\Rightarrow \mathbf{P} = \frac{3mg}{2}\sin 48.2^{\circ} = 1.118mg
$$

Elastic Potential Energy = E.P.E. = 
$$
\frac{\lambda x^2}{2a} = \frac{3mg(0.45 - 0.3)^2}{2(0.3)}
$$

$$
= 0.1125mg
$$

(i)



- (ii) Resolving vertically  $\mathbf{R} = 0.4g = 4 \text{ N}$ But the frictional force  $\mathbf{F} = \mu \mathbf{R} = (0.5)(4) = 2 \text{ N}$
- (iii) Consider the 0.3 kg block

Resolving vertically and applying Newton's second law **F** = *ma* 

$$
0.3g - \mathbf{T} = 0.3a \qquad ...(a)
$$

Consider the 0.4 kg block

Resolving horizontally and applying Newton's second law **F** = *ma* 

 $T - \mu R = 0.4a$ 

 $T - 2 = 0.4a$  by using part (ii) …(b)

(a) + (b): 
$$
0.3g - 2 = 0.7a \implies a = \frac{0.3g - 2}{0.7} = \frac{10}{7} \text{ m/s}^2
$$

(iv) Applying  $v = u + at$ , we get  $v = 0 + \frac{16}{5}$   $\left|7 = \frac{10 \text{ m/s}}{5}\right|$ 7  $0 + \left(\frac{10}{7}\right)7 =$ J  $\left(\frac{10}{2}\right)$ l ſ  $v = 0 +$ 

> (v) The 0.3 kg block would accelerate further. In fact its speed would increase at a faster rate since  $T = 0$

 The 0.4 kg block would decelerate. In fact its speed would decrease since  $T = 0$  and the only horizontal force acting on the particle would be the frictional force.



(i) At equilibrium, resolving along the line of slope

$$
\frac{P}{V} - R = (800g \sin \theta) \implies \frac{10000}{V} - R = 8000 \left(\frac{1}{40}\right) = 200 \dots (a)
$$



At equilibrium, resolving along the line of slope

$$
\mathbf{R} - \frac{\mathbf{P}}{2V} = (800g \sin \theta) \implies \mathbf{R} - \frac{5000}{V} = 8000 \left(\frac{1}{40}\right) = 200 \dots (b)
$$
  
(a) + (b)  $\frac{10000}{V} - \frac{5000}{V} = 400 \implies \frac{5000}{V} = 400$   
i.e.  $V = \frac{5000}{400} = \frac{25}{2} = \frac{12.5 \text{ m/s}}{}$ 

Substituting in (a): 
$$
\frac{10000}{12.5} - \mathbf{R} = 200 \implies \mathbf{R} = \underline{600 \text{ N}}
$$
  
(ii)  

$$
\begin{array}{c}\nV = 12.5 \text{ m/s} \\
\hline\n\end{array}
$$

Applying Newton's 2<sup>nd</sup> law **F** = ma  
\n
$$
\frac{P}{V} - 600 = 8000a
$$
\n
$$
\frac{10000}{12.5} - 600 = 8000a \implies 800 - 600 = 800a \text{ i.e. } a = 0.25 \text{ m/s}^2
$$

(i) Consider the horizontal axes:

 $x = 36$  m (Given)

 $\dot{x} = u \cos \alpha$ , where *u* is the initial velocity and  $\alpha$  is the angle of projection.

$$
\begin{aligned}\n\dot{x} &= 24 \cos 30^\circ = 24 \left( \frac{\sqrt{3}}{2} \right) = 12 \sqrt{3} \\
x &= (u \cos \alpha)t = (12 \sqrt{3})t \\
\therefore 36 &= (12 \sqrt{3})t \implies t = \frac{36}{12 \sqrt{3}} = \frac{3}{\sqrt{3}} = \frac{3}{\sqrt{3}} \times \frac{\sqrt{3}}{\sqrt{3}} = \frac{\sqrt{3} \text{ s}}{\sqrt{3}}\n\end{aligned}
$$

(ii) Consider the vertical axes:

$$
s = h, \quad u = 24 \sin 30^{\circ}, \quad a = -10 \text{ m/s}^2, \quad t = \sqrt{3}
$$
  
Using  $s = ut + \frac{1}{2}at^2$   
we get  $h = (24 \sin 30^{\circ})(\sqrt{3}) + \frac{1}{2}(-10)(\sqrt{3})^2$   
 $h = 12(1.732) - 5(3) = 5.785 \text{ m}$   
(iii)  $\dot{x} = u \cos \alpha = 24 \cos 30^{\circ} = 20.785$   
 $\dot{y} = u \sin \alpha - gt = 24 \sin 30^{\circ} - 10(\sqrt{3}) = -5.321$   
Speed =  $\sqrt{\dot{x}^2 + \dot{y}^2} = \sqrt{(20.785)^2 + (-5.321)^2} = 21.455 \text{ m/s}$   
(iv)



$$
\tan \alpha = \frac{5.321}{20.785} = 0.256 \implies \alpha = 14.36^{\circ}
$$
 below the horizontal.

(i)  $1<sup>st</sup>$  collision



 $e = \frac{\text{separation speed}}{1.0 \text{ g}} = \frac{v_1 - u_1}{2} \Rightarrow v_1 - u_1 = eu$ *u*  $e = \frac{\text{SeparationSpeed}}{\text{100}} = \frac{v_1 - u_1}{v_1 - u_1} \Rightarrow v_1 - u_1 =$ −  $=\frac{\text{SeparationSpeed}}{\text{Area} + \text{Area} + \$ ApproachSpeed  $u - 0$ SeparationSpeed  $= \frac{v_1 - u_1}{v_1 - u_1} \Rightarrow v_1 - u_1 = eu$  ...(a)

Applying conservation of Momentum, we get

$$
mu + m(0) = mu_1 + mv_1 \implies u_1 + v_1 = u \quad ...(b)
$$
  
(a) + (b)  $2v_1 = eu + u = u(1 + e) \implies v_1 = \frac{u}{2}(1 + e)$ 

(ii)  $2<sup>nd</sup>$  collision



$$
e = \frac{w_2 - v_2}{v_1 - 0} \implies w_2 - v_2 = ev_1 \quad ...(c)
$$

Applying conservation of Momentum, we get

 $mv_1 + 2m(0) = mv_2 + 2mw_2 \implies v_2 + 2w_2 = v_1$  ...(d)

(c) + (d) 
$$
w_2 + 2w_2 = v_1(1+e) = \frac{u}{2}(e+1)(e+1)
$$
  
\n
$$
\Rightarrow 3\left(\frac{3}{8}u\right) = \frac{u}{2}(1+e)^2 \quad \text{i.e. } \frac{9}{8} = \frac{(1+e)^2}{2}
$$
\n
$$
(1+e)^2 = \frac{9}{4} \quad \Rightarrow (1+e) = \frac{3}{2} \quad \text{i.e. } e = \frac{1}{2}
$$



(i) Applying Newton's second law  $\mathbf{F} = ma$ , we get

$$
135 - 9v = 81 \frac{dv}{dt}
$$
  
Divide by 135 - 9v :  

$$
1 = \frac{81}{135 - 9v} \frac{dv}{dt}
$$
  
It simplifies to
$$
1 = \frac{9}{15 - v} \frac{dv}{dt}
$$

(ii) Integrating both sides of the differential equation

$$
\int_0^t dt = \int_0^v \frac{9}{15 - v} dv
$$
  
\n
$$
t = -9 \ln |15 - v| \Big|_0^v = -9 \ln |15 - v| + 9 \ln 15 = 9 \ln \left| \frac{15}{15 - v} \right|
$$
  
\n
$$
\Rightarrow \ln \left| \frac{15}{15 - v} \right| = \frac{t}{9} \quad \text{i.e.} \quad \frac{15}{15 - v} = e^{\frac{t}{9}}
$$
  
\n
$$
15 = (15 - v)e^{\frac{t}{9}} \quad \text{or} \quad 15e^{-\frac{t}{9}} = 15 - v
$$
  
\n
$$
v = 15 - 15e^{-\frac{t}{9}} = \frac{15 \left(1 - e^{-\frac{t}{9}}\right)}{15 - 15e^{-\frac{t}{9}}} = \frac{15 \left(1 - e^{-\frac{t}{9}}\right)}{15 - 15e^{-\frac{t}{9}}}
$$

As 
$$
t \to \infty
$$
  $e^{-\frac{t}{9}} \to 0$   $\therefore$   $v = \frac{15 \text{ m/s}}{}$ 

(iii) 
$$
v = \frac{dx}{dt} = 15(1 - e^{-\frac{t}{9}})
$$
 by using part (ii)

Integrating this differential equation

$$
\int_0^x dx = \int_0^9 15(1 - e^{-\frac{t}{9}})dt
$$
  
\n
$$
\Rightarrow x = \int_0^9 15(1 - e^{-\frac{t}{9}})dt = \int_0^9 (15 - 15e^{-\frac{t}{9}})dt
$$
  
\n
$$
x = \left[15t - 15\frac{e^{-\frac{t}{9}}}{-\frac{1}{9}}\right]_0^9 = \left[15t + 135e^{-\frac{t}{9}}\right]_0^9
$$
  
\n
$$
x = 15(9) + 135e^{-1} - 15(0) - 135e^0 = 135 + 135e^{-1} - 135 = \frac{49.66 \text{ m}}{23}
$$

Question 14

(i) Given 
$$
v_M = 6\mathbf{i} + 12\mathbf{j}
$$
 and  $v_H = 12\mathbf{i} - 8\mathbf{j}$   
\nThe velocity of Harvey relative to Mario =  $v_{H-M} = v_H - v_M$   
\n
$$
= (12 - 6)\mathbf{i} + (-8 - 12)\mathbf{j} = \frac{(6\mathbf{i} - 20\mathbf{j}) \text{ km/h}}{2}
$$
\nGiven  $r_M$  ( $t = 0$ ) = 5\mathbf{i} - \mathbf{j} and  $r_H$  ( $t = 0$ ) = 18\mathbf{i} + 5\mathbf{j}  
\nThe initial position of Harvey relative to Mario =  $r_{H-M} = r_H - r_M$   
\n
$$
= (18 - 5)\mathbf{i} + (5 + 1)\mathbf{j} = \frac{(13\mathbf{i} + 6\mathbf{j}) \text{ km}}{2}
$$
\n(ii) In general  $r(t) = r(t = 0) + tv$ 

$$
\therefore H r_M(t) = H r_M(t) = 0 + t_H v_M
$$
  
\n
$$
\Rightarrow H r_M(t) = 13\mathbf{i} + 6\mathbf{j} + t(6\mathbf{i} - 20\mathbf{j}) = (13 + 6t)\mathbf{i} + (6 - 20t)\mathbf{j} + 6\mathbf{k}
$$

# (iii) Diagram relative to M



Closest approach occurs when  $_{H} r_{M}(t)$  is perpendicular to  $_{H} v_{M}(t)$ 

i.e. when 
$$
_{H}r_{M}(t) \cdot {}_{H}v_{M}(t) = 0
$$
  
\ni.e.  $\{(13+6t)\mathbf{i} + (6-20t)\mathbf{j}\} \cdot \{6\mathbf{i} - 20\mathbf{j}\} = 0$   
\n $(13+6t)(6) + (6-20t)(-20) = 0$   
\n $78 + 36t - 120 + 400t = 0$   
\n $436t = 42 \implies t = \frac{42}{436} = 0.0963 \text{ hr} = 5.78 \text{ mins}$